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TS Manuals.[The histological and ultrastructural characteristics of the adrenal medulla: a study in human subjects with obesity and glucose intolerance]. The adrenal medulla consists of noradrenergic nerve endings with a dense core of synaptic vesicles and adrenergic nerve endings with small and large dense core vesicles. The noradrenergic nerve endings are distributed uniformly in the medullary parenchyma. The adrenergic nerves prevail in the cortex, especially in Zones 1 and 2 of the glomeruli of the adrenal cortex. Both noradrenergic and adrenergic nerve endings are more numerous in obese subjects, but the percentages of both types of nerve endings in obese subjects are lower than in non-obese subjects. The adrenal medulla of obese subjects is characterized by homogenization of the nerve endings and their decrease in diameter. The biopsy of obese subjects, showed intensive dystrophic changes of the nerve ending ultrastructure. The number and diameter of large dense core vesicles on the surface of nerve endings are reduced, while the number of small dense core vesicles is increased in obese subjects. Changes in the ultrastructure of the adrenal medulla of obese subjects are considered to be pathological.The present invention relates to industrial vehicles and more particularly to apparatus and methods for controlling the operation of industrial vehicles using position control actuators such as electric drive motors. In many industrial applications it is desired to control the movement of industrial vehicles along a path. For example, in certain

industrial applications it is important for the vehicle to maintain a desired xe2x80x9cpathxe2x80x9d for the vehicle and to move in such a way as to avoid collisions. It is also desirable in certain applications to know the current position of the vehicle so that the vehicle can be returned to a particular path without re-meshing the path. Truck or other heavy industrial vehicles are often used for moving heavy loads from one location to another, and in moving loads within a building or around a factory. In such applications, it is important for the operator or driver of the vehicle to be able to position the vehicle in a desired location and to have accurate knowledge of where the vehicle is at any given time. A variety of techniques have been employed to provide for such accurate positioning of the vehicle. The operator of the vehicle typically employs an instrument or monitor which is coupled to an antenna on the vehicle and communicates with the vehicle position over